

Causal Inference under Low-Order Interference

SINM Symposium
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Matt
Eichhorn



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Khan



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Ugander



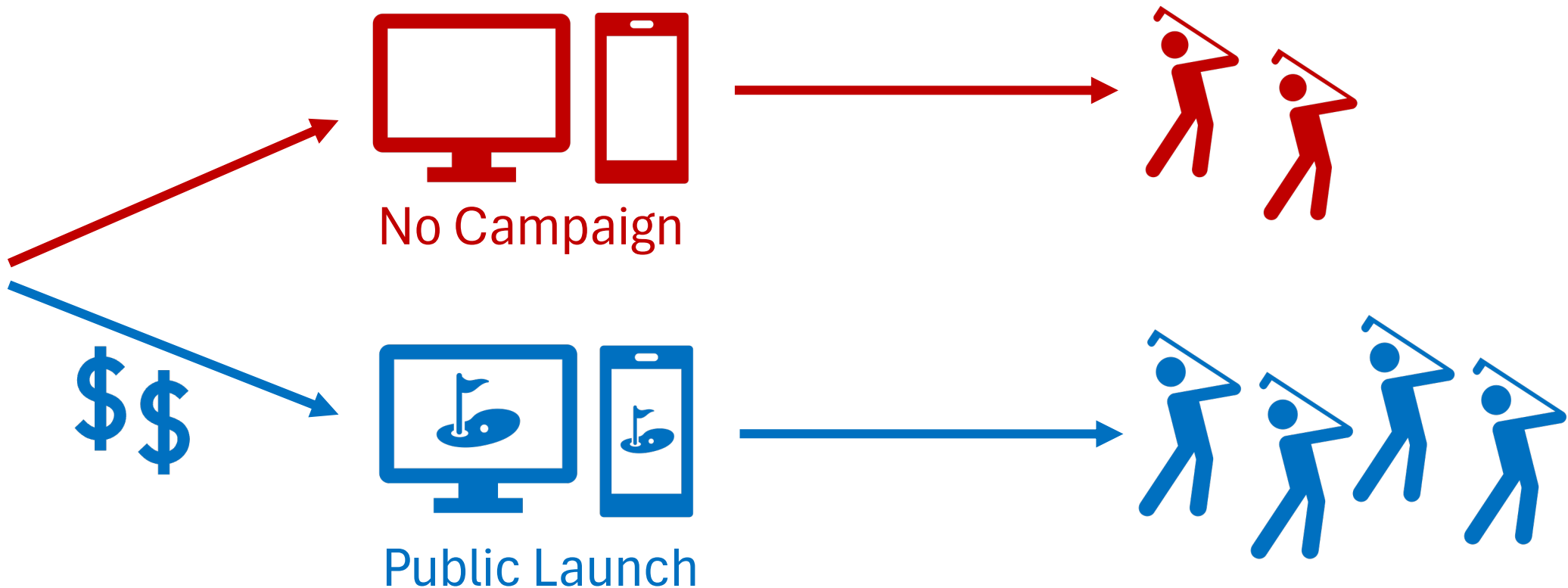
Christina
Lee Yu

Talk Structure

1. Motivation: causal inference under interference
2. β -Order interactions
3. Estimation with Bernoulli experimental designs
4. Estimation with arbitrary experimental designs
5. Selecting an experimental design

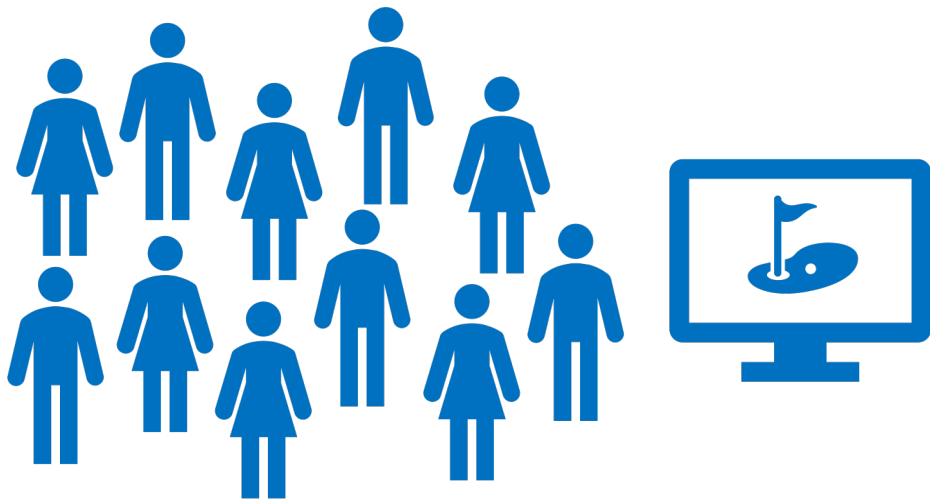
Motivating Example: Advertising

A golf course is deciding whether to run an advertising campaign



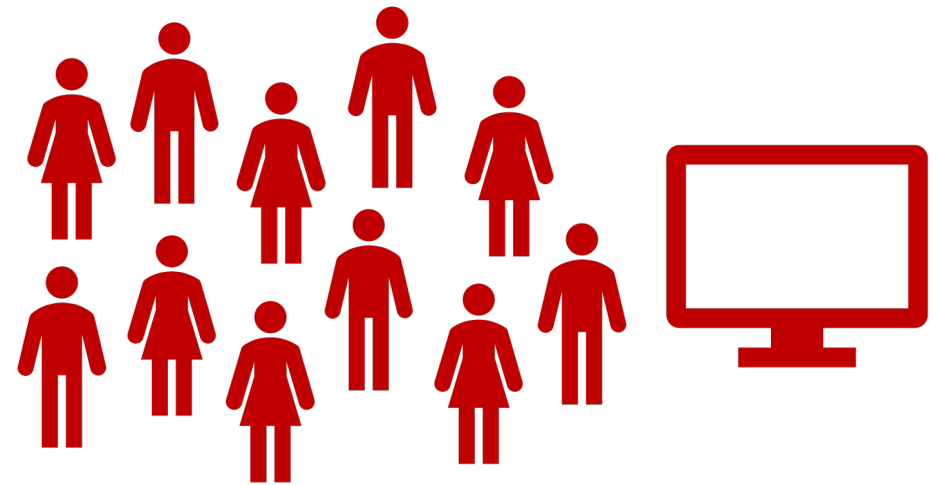
Total Treatment Effect

Difference in *average outcome* (e.g., monthly spending at the course) under two possible *global actions*:



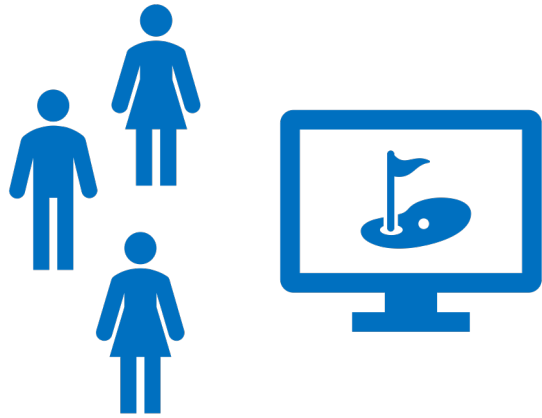
Everybody Treated

vs.

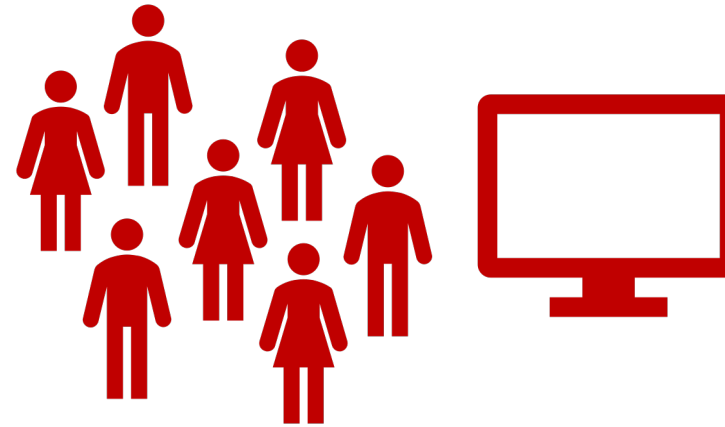


Nobody Treated

Randomized Experiment



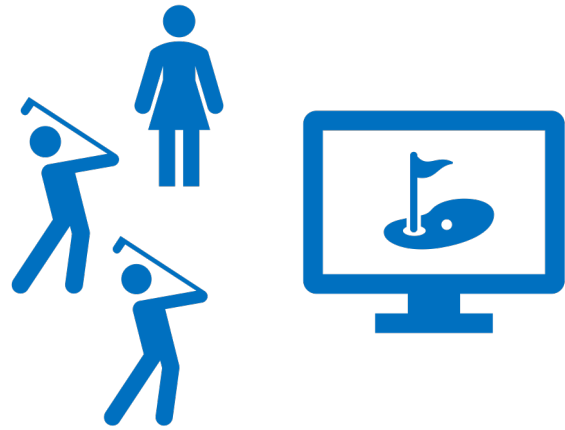
Treatment Group



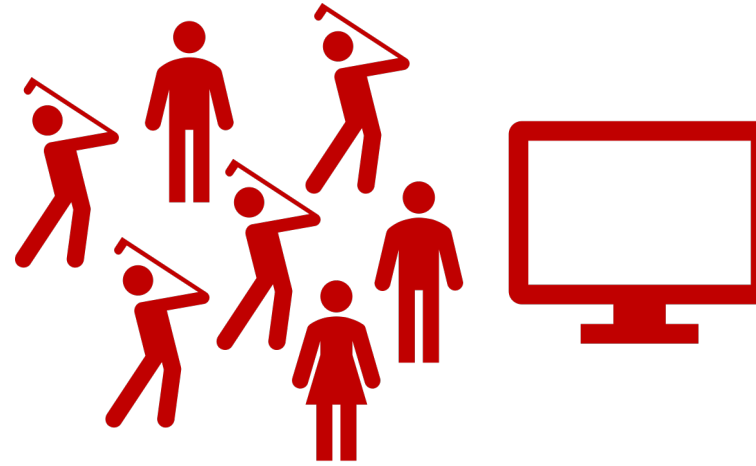
Control Group

*** Assume the marginal probability p of being in the treatment group is small.

Randomized Experiment



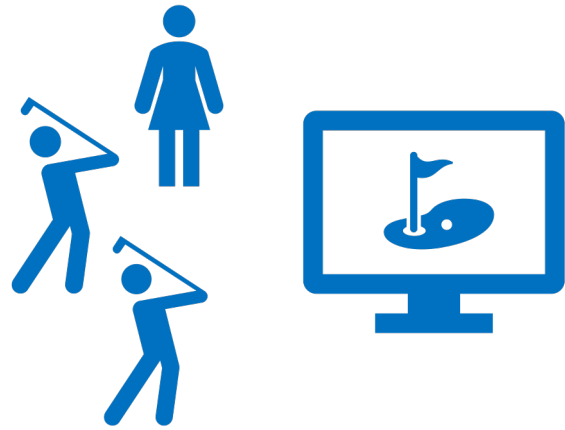
Treatment Group



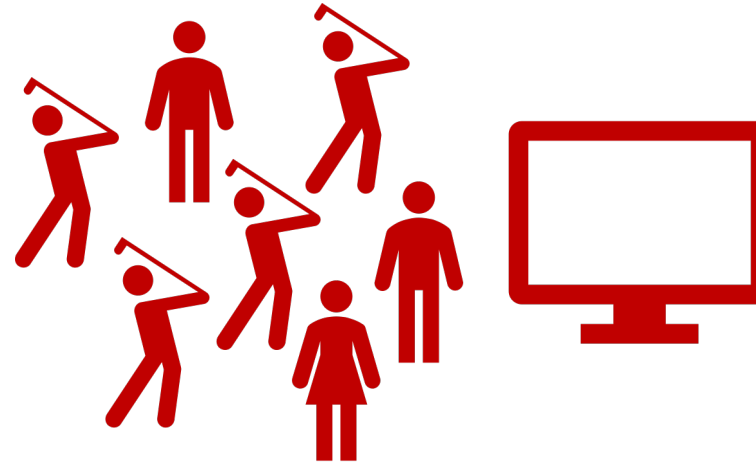
Control Group

*** Assume the marginal probability p of being in the treatment group is small.

Randomized Experiment



Treatment Group



Control Group

*** Assume the marginal probability p of being in the treatment group is small.

Difference in Means Estimator:

$$\widehat{TTE}_{DM} = \text{Average Outcome in Treatment Group} - \text{Average Outcome in Control Group}$$

Interference

Individuals' outcomes may change even if they are not treated



Interference

Individuals' outcomes may change even if they are not treated



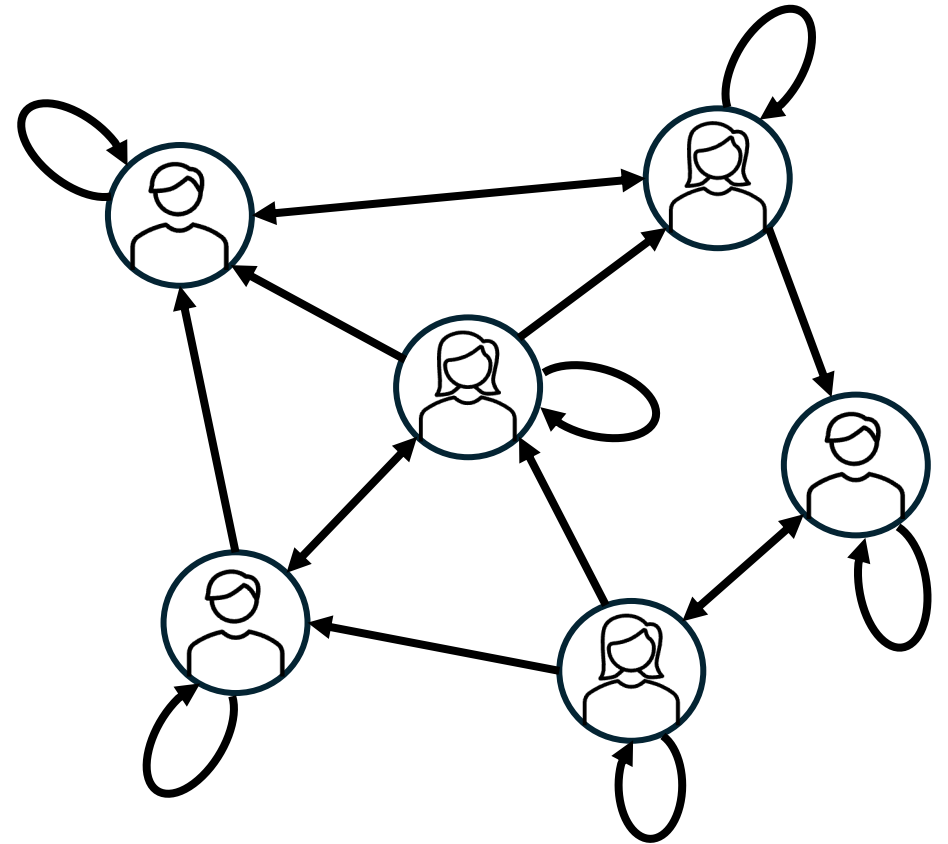
Introduces Bias into DM Estimator

Modeling Interference

Directed Interference Graph $G = (V, A)$

$V = n$ individuals

$(j, i) \in A \Rightarrow j$'s treatment affects i 's outcome



Ugander, Johan, et al. "Graph cluster randomization: Network exposure to multiple universes." *Proceedings of the 19th ACM SIGKDD international conference on Knowledge discovery and data mining*. 2013.

Aronow, Peter M., and Cyrus Samii. "Estimating average causal effects under general interference, with application to a social network experiment." (2017): 1912-1947.

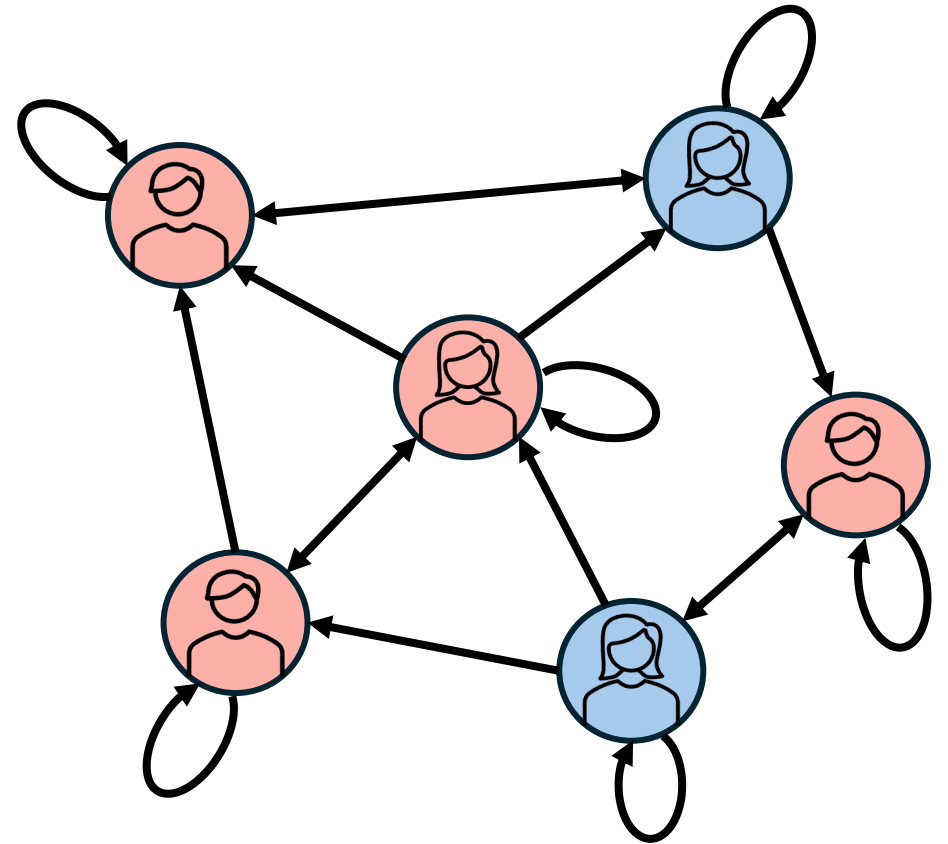
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Treatment Assignments $\mathbf{z} \in \{0, 1\}^n$



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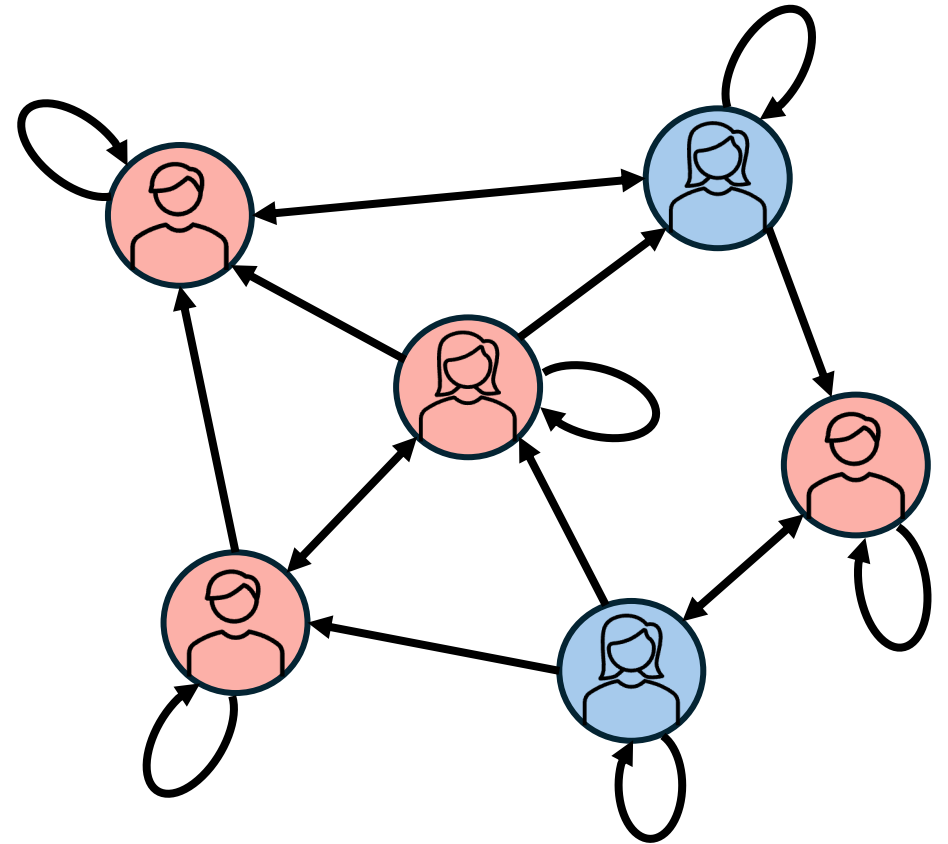
Treatment Assignments $\mathbf{z} \in \{0, 1\}^n$

Potential Outcomes $Y_i(\mathbf{z}) : \{0, 1\}^n \rightarrow \mathbb{R}$

* We'll assume these functions are *bounded*

Neighborhood Interference Assumption:

$$z_j = z'_j \text{ for all } j \in N_i \Rightarrow Y_i(\mathbf{z}) = Y_i(\mathbf{z}')$$



Sussman, Daniel L., and Edoardo M. Airoldi. "Elements of estimation theory for causal effects in the presence of network interference." *arXiv preprint arXiv:1702.03578* (2017).

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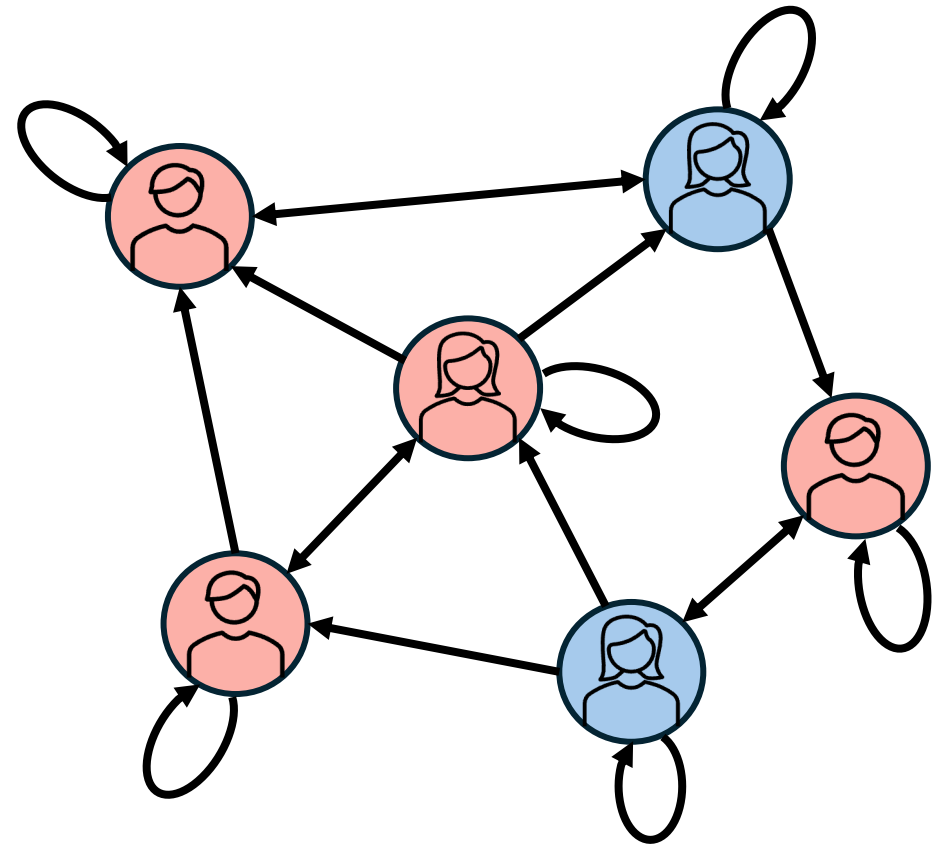
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* We'll assume these functions are *bounded*.

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Total Treatment Effect:

$$\text{TTE} = \frac{1}{n} \sum_{i=1}^n (Y_i(\mathbf{1}) - Y_i(\mathbf{0}))$$

Horvitz-Thompson Estimator

$$\widehat{\text{TTE}}_{\text{HT}} = \frac{1}{n} \sum_{i=1}^n Y_i(\mathbf{z}) \left(\frac{\mathbb{I}(N_i \text{ fully treated})}{\text{Pr}(N_i \text{ fully treated})} - \frac{\mathbb{I}(N_i \text{ fully untreated})}{\text{Pr}(N_i \text{ fully untreated})} \right)$$

Horvitz, Daniel G., and Donovan J. Thompson. "A generalization of sampling without replacement from a finite universe." *Journal of the American statistical Association* 47.260 (1952): 663-685.

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Under Independent Treatment Assignments $z_j \sim \text{Bernoulli}(p)$:

$$= \frac{1}{n} \sum_{i=1}^n Y_i(\mathbf{z}) \left(\underbrace{\prod_{j \in N_i} \frac{z_j}{p}}_{\substack{\text{0 unless entire} \\ \text{neighborhood} \\ \text{treated}}} - \underbrace{\prod_{j \in N_i} \frac{1-z_j}{1-p}}_{\substack{\text{0 unless entire} \\ \text{neighborhood} \\ \text{untreated}}} \right)$$

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- Unbiased estimator
- Prohibitive $O(p^{-d})$ variance

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Variance Reduction Strategies

1. Smarter Estimator Design

- Horvitz-Thompson Estimator ignores a lot of useful observations
- Smarter estimators incorporate measurements from partially treated neighborhoods
- Relies on structural assumptions on **potential outcomes**

2. Smarter Experimental Design

- Under Bernoulli treatment, most neighborhoods are partially treated
- Smarter designs increase prevalence of fully treated neighborhoods
- Relies on structural assumptions on **interference network**

Related Work

		Network Structure		
		C Disconnected Subcommunities	κ -Restricted Growth	Fully General
Outcomes Structure	Linear	Directions for Future Work		OLS Estimation Bernoulli Design
	Generalized Linear			Feature Regression Bernoulli Design
	β -Order Interactions	Pseudoinverse Estimators for General Designs		SNIFE Estimator Bernoulli Designs
	General Neighborhood Interference	HT Estimator Cluster Designs	HT Estimator (Randomized) Cluster Designs	HT Estimator Bernoulli Design

Many citations arranged in final bibliography

β -Order Interactions

Cortez, Mayleen, **Matthew Eichhorn**, and Christina Yu. "Staggered rollout designs enable causal inference under interference without network knowledge." *Advances in Neural Information Processing Systems* 35 (2022): 7437-7449.

Cortez-Rodriguez, Mayleen, **Matthew Eichhorn**, and Christina Lee Yu. "Exploiting neighborhood interference with low-order interactions under unit randomized design." *Journal of Causal Inference* 11.1 (2023): 20220051.

Potential Outcomes under Network Interference

Since treatments are binary, $z_j \in \{0,1\}$, we can write:

$$Y_i(\mathbf{z}) = \sum_{T \subseteq N_i} a_{i,T} \underbrace{\prod_{j \in T} z_j}_{T \text{ fully treated}} \underbrace{\prod_{j' \in N_i \setminus T} (1 - z_{j'})}_{N_i \setminus T \text{ fully control}}$$

Potential Outcomes under Network Interference

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Re-parameterize in the *monomial basis*:

$$Y_i(\mathbf{z}) = \sum_{S \subseteq N_i} c_{i,S} \prod_{j \in S} z_j \quad c_{i,S} = \text{additive effect on } i \text{ when } S \text{ is treated (regardless of other treatments)}$$

β -Order Interactions

Intuition: Influence comes from small subsets of neighbors

Imposes a sparsity assumption on the $c_{i,S}$ coefficients

$$c_{i,S} = 0 \text{ whenever } |S| > \beta$$

$$Y_i(\mathbf{z}) = \sum_{\substack{S \subseteq N_i \\ |S| \leq \beta}} c_{i,S} \prod_{j \in S} z_j = \sum_{S \in \mathcal{S}_i^\beta} c_{i,S} (\tilde{\mathbf{z}}_i)_S = \langle \mathbf{c}_i, \tilde{\mathbf{z}}_i \rangle$$

β -Order Interactions

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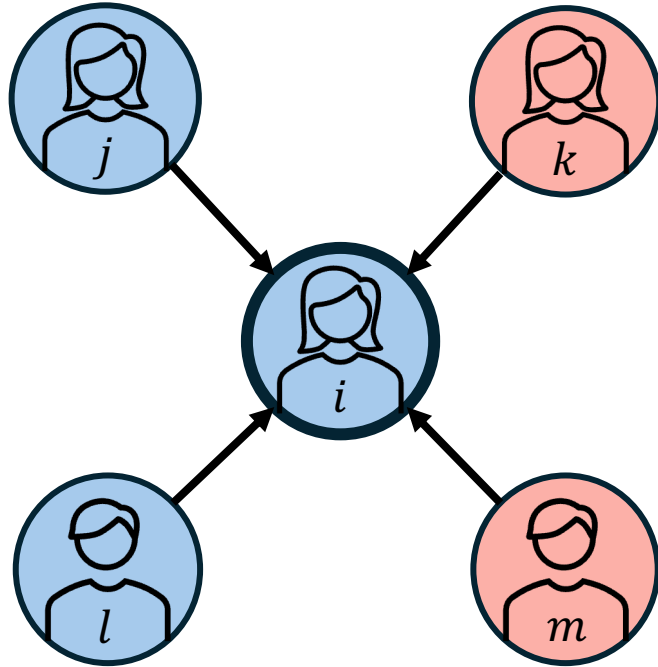
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$(\tilde{\mathbf{z}}_i)_S = \prod_{j \in S} z_j$ indicates if *everyone* in S is treated

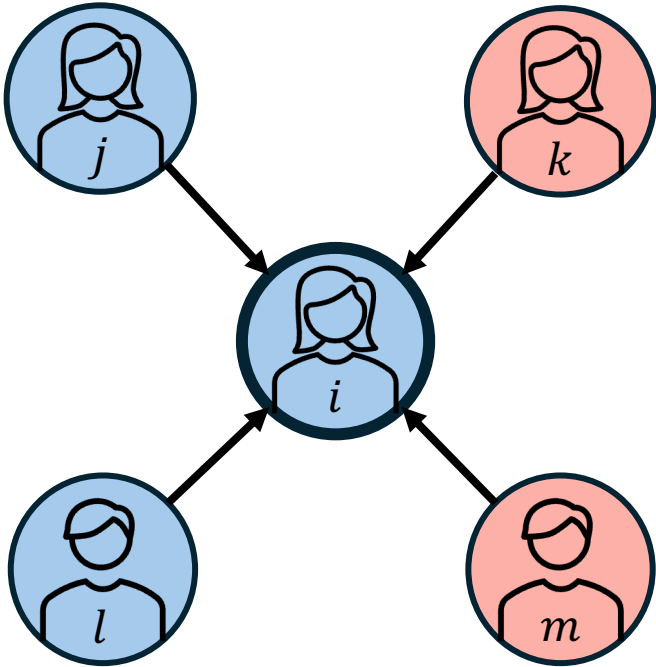
Example



$$\beta = 1:$$

$$Y_i(z) = \underbrace{c_{i,\emptyset}}_{\text{Baseline}} + \underbrace{c_{i,\{i\}} + c_{i,\{j\}} + c_{i,\{l\}}}_{\text{Treatment Effect}}$$

Example



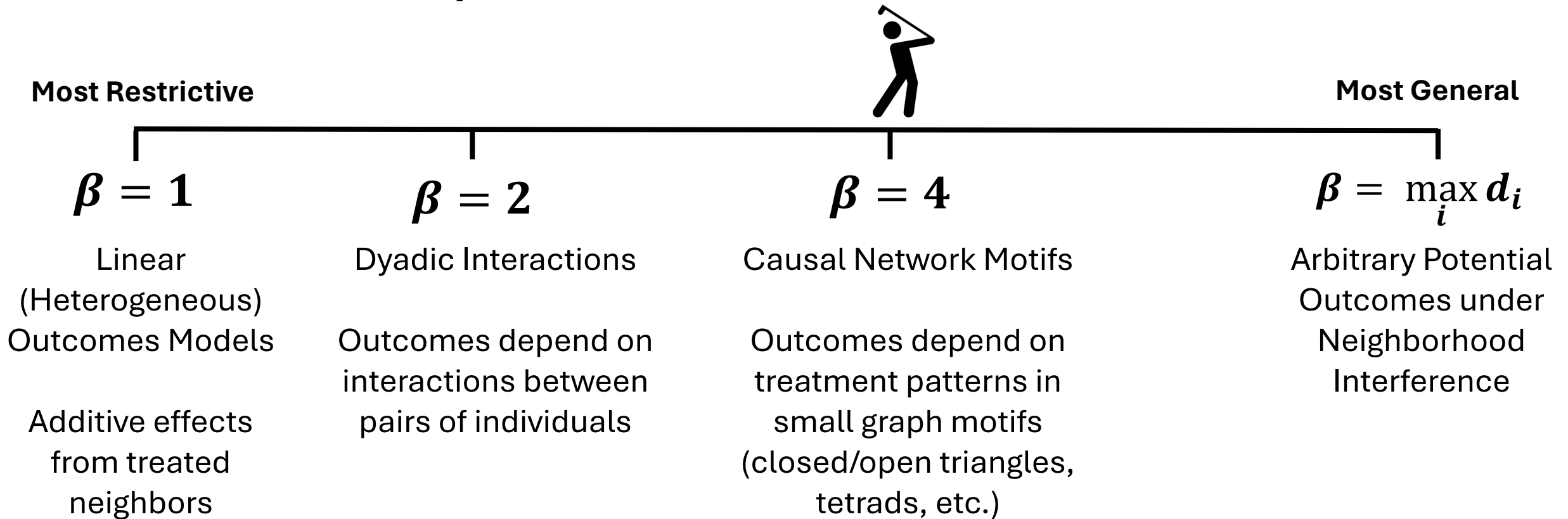
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$\beta = 2$:

$$Y_i(z) = c_{i,\emptyset} + c_{i,\{i\}} + c_{i,\{j\}} + c_{i,\{l\}} \\ + c_{i,\{i,j\}} + c_{i,\{i,l\}} + c_{i,\{j,l\}}$$

Interpreting β



Yu, Christina Lee, et al. "Estimating the total treatment effect in randomized experiments with unknown network structure." *PNAS* 119.44 (2022):

Deng, Lu, et al. "Unbiased Estimation for Total Treatment Effect Under Interference Using Aggregated Dyadic Data." *arXiv preprint arXiv:2402.12653* (2024).

Yuan, Yuan, Kristen Altenburger, and Farshad Kooti. "Causal network motifs: Identifying heterogeneous spillover effects in a/b tests." *Proceedings of the Web Conference 2021*.

Total Treatment Effect

$$\text{TTE} = \frac{1}{n} \sum_{i=1}^n (Y_i(\mathbf{1}) - Y_i(\mathbf{0})) = \frac{1}{n} \sum_{i=1}^n \sum_{\substack{S \subseteq N_i \\ 1 \leq |S| \leq \beta}} c_{i,S} = \frac{1}{n} \sum_{i=1}^n \langle \mathbf{c}_i, \underbrace{\boldsymbol{\theta}_i}_{\substack{(\theta_i)_\emptyset = 0 \\ (\theta_i)_S = 1}} \rangle$$

We'll develop an estimator for each \mathbf{c}_i that can be extended by linearity to a TTE estimator.

Estimating TTE under Bernoulli randomization

Cortez-Rodriguez, Mayleen, **Matthew Eichhorn**, and Christina Lee Yu. "Exploiting neighborhood interference with low-order interactions under unit randomized design." *Journal of Causal Inference* 11.1 (2023): 20220051.

Designing an Estimator

Imagine we could replicate our randomized experiment R times

$$\underbrace{\begin{bmatrix} Y_i(\mathbf{z}^{(1)}) \\ Y_i(\mathbf{z}^{(2)}) \\ \vdots \\ Y_i(\mathbf{z}^{(R)}) \end{bmatrix}}_{\mathbf{Y}_i} = \begin{bmatrix} \leftarrow \tilde{\mathbf{z}}_i^{(1)} \rightarrow \\ \leftarrow \tilde{\mathbf{z}}_i^{(2)} \rightarrow \\ \vdots \\ \leftarrow \tilde{\mathbf{z}}_i^{(R)} \rightarrow \end{bmatrix} \begin{bmatrix} \uparrow \\ \mathbf{c}_i \\ \downarrow \end{bmatrix}$$

\mathbf{Z}_i^R

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Left-Multiply by $\frac{1}{R} (\mathbf{Z}_i^R)^\top$

$$\begin{aligned} \frac{1}{R} \sum_{r=1}^R Y_i(\mathbf{z}^{(r)}) \cdot \tilde{\mathbf{z}}_i^{(r)} &= \frac{1}{R} \sum_{r=1}^R \tilde{\mathbf{z}}_i^{(r)} \cdot \left(\tilde{\mathbf{z}}_i^{(r)} \right)^\top \mathbf{c}_i \\ \downarrow \text{a.s.} & \qquad \qquad \qquad \downarrow \text{a.s.} \\ \mathbb{E}[Y_i(\mathbf{z}) \tilde{\mathbf{z}}_i] &= \mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top] \mathbf{c}_i \end{aligned}$$

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$$\underbrace{\begin{bmatrix} Y_i(\mathbf{z}^{(1)}) \\ Y_i(\mathbf{z}^{(2)}) \\ \vdots \\ Y_i(\mathbf{z}^{(R)}) \end{bmatrix}}_{\mathbf{Y}_i} = \begin{bmatrix} \leftarrow \tilde{\mathbf{z}}_i^{(1)} \rightarrow \\ \leftarrow \tilde{\mathbf{z}}_i^{(2)} \rightarrow \\ \vdots \\ \leftarrow \tilde{\mathbf{z}}_i^{(R)} \rightarrow \end{bmatrix} \underbrace{\begin{bmatrix} \uparrow \\ \mathbf{c}_i \\ \downarrow \end{bmatrix}}_{\mathbf{z}_i^R}$$

Left-Multiply by $\frac{1}{R} (\mathbf{z}_i^R)^\top$

$$\frac{1}{R} \sum_{r=1}^R Y_i(\mathbf{z}^{(r)}) \cdot \tilde{\mathbf{z}}_i^{(r)} = \frac{1}{R} \sum_{r=1}^R \tilde{\mathbf{z}}_i^{(r)} \cdot \left(\tilde{\mathbf{z}}_i^{(r)}\right)^\top \mathbf{c}_i$$

$$\downarrow \text{a.s.} \qquad \qquad \qquad \downarrow \text{a.s.}$$

$$\mathbb{E}[Y_i(\mathbf{z}) \tilde{\mathbf{z}}_i] = \underbrace{\mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top]}_{\text{“Design Matrix”}} \mathbf{c}_i$$

The Design Matrix: $\mathbb{E} \left[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top \right]$

Entries indexed by subsets of N_i :

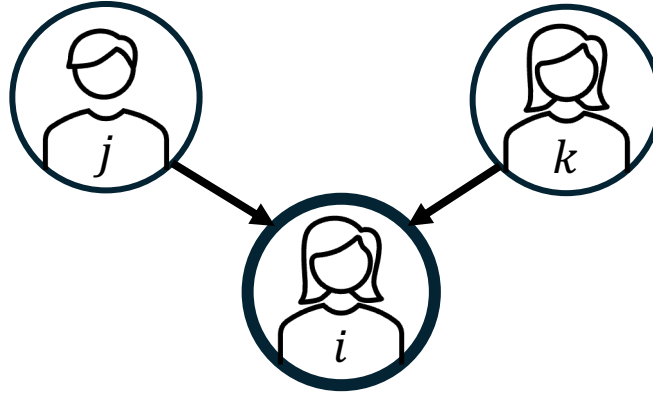
$$\left(\mathbb{E} \left[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top \right] \right)_{S,T} = \Pr(S \cup T \text{ fully treated})$$

*** Depends only on the experimental design, not the observed outcomes

For (independent) Bern(p) treatment assignments

$$\left(\mathbb{E} \left[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top \right] \right)_{S,T} = p^{|S \cup T|}$$

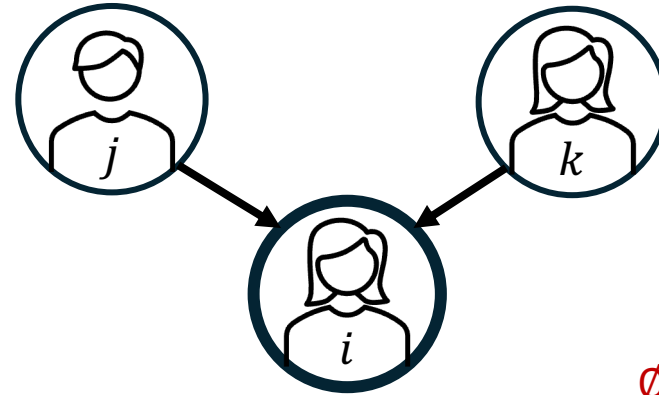
Example:



$\beta = 1:$

$$\mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^T] = \begin{array}{c} \begin{array}{cccc} \emptyset & \{i\} & \{j\} & \{k\} \end{array} \\ \begin{bmatrix} 1 & p & p & p \\ p & p & p^2 & p^2 \\ p & p^2 & p & p^2 \\ p & p^2 & p^2 & p \end{bmatrix} \begin{array}{c} \emptyset \\ \{i\} \\ \{j\} \\ \{k\} \end{array} \end{array}$$

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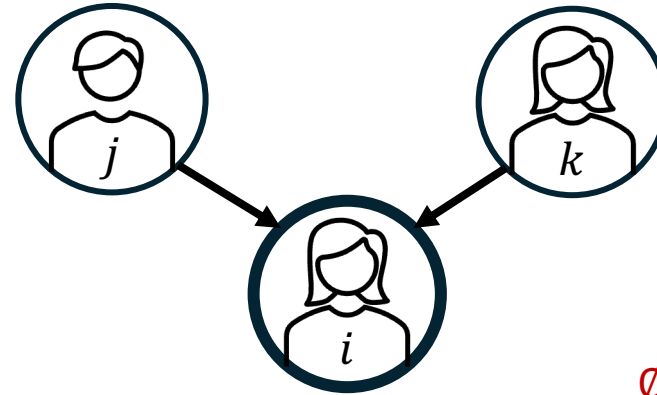
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$$\mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^T] = \begin{matrix} & \emptyset & \{i\} & \{j\} & \{k\} \\ \begin{bmatrix} 1 & p & p & p \\ p & p & p^2 & p^2 \\ p & p^2 & p & p^2 \\ p & p^2 & p^2 & p \end{bmatrix} & \emptyset \\ & \{i\} \\ & \{j\} \\ & \{k\} \end{matrix}$$

$\beta = 2:$

$$\mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^T] = \begin{matrix} & \emptyset & \{i\} & \{j\} & \{k\} & \{i,j\} & \{i,k\} & \{j,k\} \\ \begin{bmatrix} 1 & p & p & p & p^2 & p^2 & p^2 \\ p & p & p^2 & p^2 & p^2 & p^2 & p^3 \\ p & p^2 & p & p^2 & p^2 & p^3 & p^2 \\ p & p^2 & p^2 & p & p^3 & p^2 & p^2 \\ p^2 & p^2 & p^2 & p^3 & p^2 & p^3 & p^3 \\ p^2 & p^2 & p^3 & p^2 & p^3 & p^2 & p^3 \\ p^2 & p^3 & p^2 & p^2 & p^3 & p^3 & p^2 \end{bmatrix} & \emptyset \\ & \{i\} \\ & \{j\} \\ & \{k\} \\ & \{i,j\} \\ & \{i,k\} \\ & \{j,k\} \end{matrix}$$

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Theorem: Under independent Bernoulli design, each design matrix is invertible.

Designing an Estimator

$$\mathbb{E}[Y_i(\mathbf{z}) \tilde{\mathbf{z}}_i] = \mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top] \mathbf{c}_i \quad \Rightarrow \quad \mathbf{c}_i = \mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top]^{-1} \mathbb{E}[Y_i(\mathbf{z}) \tilde{\mathbf{z}}_i]$$

Designing an Estimator

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Replace with single realization

$$\hat{\mathbf{c}}_i = Y_i(\mathbf{z}) \mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top]^{-1} \tilde{\mathbf{z}}_i$$

Designing an Estimator

$$\mathbb{E}[Y_i(\mathbf{z}) \tilde{\mathbf{z}}_i] = \mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top] \mathbf{c}_i \quad \Rightarrow \quad \mathbf{c}_i = \mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top]^{-1} \underbrace{\mathbb{E}[Y_i(\mathbf{z}) \tilde{\mathbf{z}}_i]}$$

Replace with single realization

$$\hat{\mathbf{c}}_i = Y_i(\mathbf{z}) \mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top]^{-1} \tilde{\mathbf{z}}_i$$

$$\widehat{\text{TTE}} = \frac{1}{n} \sum_{i=1}^n \langle \hat{\mathbf{c}}_i, \boldsymbol{\theta}_i \rangle = \frac{1}{n} \sum_{i=1}^n Y_i(\mathbf{z}) \left\langle \mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top]^{-1} \boldsymbol{\theta}_i, \tilde{\mathbf{z}}_i \right\rangle$$

Designing an Estimator

$$\mathbb{E}[Y_i(\mathbf{z}) \tilde{\mathbf{z}}_i] = \mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top] \mathbf{c}_i \quad \Rightarrow \quad \mathbf{c}_i = \mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top]^{-1} \underbrace{\mathbb{E}[Y_i(\mathbf{z}) \tilde{\mathbf{z}}_i]}$$

Replace with single realization

$$\hat{\mathbf{c}}_i = Y_i(\mathbf{z}) \mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top]^{-1} \tilde{\mathbf{z}}_i$$

$$\widehat{\text{TTE}} = \frac{1}{n} \sum_{i=1}^n \langle \hat{\mathbf{c}}_i, \boldsymbol{\theta}_i \rangle = \frac{1}{n} \sum_{i=1}^n Y_i(\mathbf{z}) \left\langle \mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top]^{-1} \boldsymbol{\theta}_i, \tilde{\mathbf{z}}_i \right\rangle$$



... Lots of Algebra ...

$$\widehat{\text{TTE}}_{\text{SNIPE}} = \frac{1}{n} \sum_{i=1}^n Y_i(\mathbf{z}) \sum_{S \in \mathcal{S}_i^\beta} \left(\prod_{j \in S} \frac{z_j - p}{p} - \prod_{j \in S} \frac{z_j - p}{p - 1} \right)$$

Structured
Neighborhood **I**nterference
Polynomial **E**stimator

Properties of the SNIPE Estimator

- Unbiased

- Variance = $O\left(\frac{d^2}{n} \cdot \left(\frac{ed}{\beta p(1-p)}\right)^\beta\right)$

n = graph size

d = maximum vertex degree

β = model degree

p = treatment probability

Properties of the SNIPE Estimator

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n = graph size

d = maximum vertex degree

β = model degree

p = treatment probability

Interpreting the Variance:

- $\frac{1}{n}$ ensures consistency of estimator
- Polynomial scaling in d , exponential scaling in β
- Minimax $\Omega\left(\frac{1}{np^\beta}\right)$ lower bound on variance
- Compare with $\Theta\left(\frac{1}{np^d}\right)$ variance of HT estimator

Analyzing the SNIPE Estimator

Dataset

- Vertices: 19,828 DVDs sold on Amazon
- Arcs: Each DVD connected to 5 most frequent co-purchases

Potential Outcomes Model

- Variation on Ugander Yin model:

$$Y_i(\mathbf{0}) = (\alpha + \beta h_i + \sigma) \cdot \frac{d_i}{\bar{d}} \quad Y_i(\mathbf{z}) = Y_i(\mathbf{0}) \left(\delta_i z_i + \sum_{S \in \mathcal{S}_i^\beta} \gamma_{|S|} \cdot \left(\frac{d_i}{|S|} \right)^{-1} \tilde{\mathbf{z}}_S \right)$$

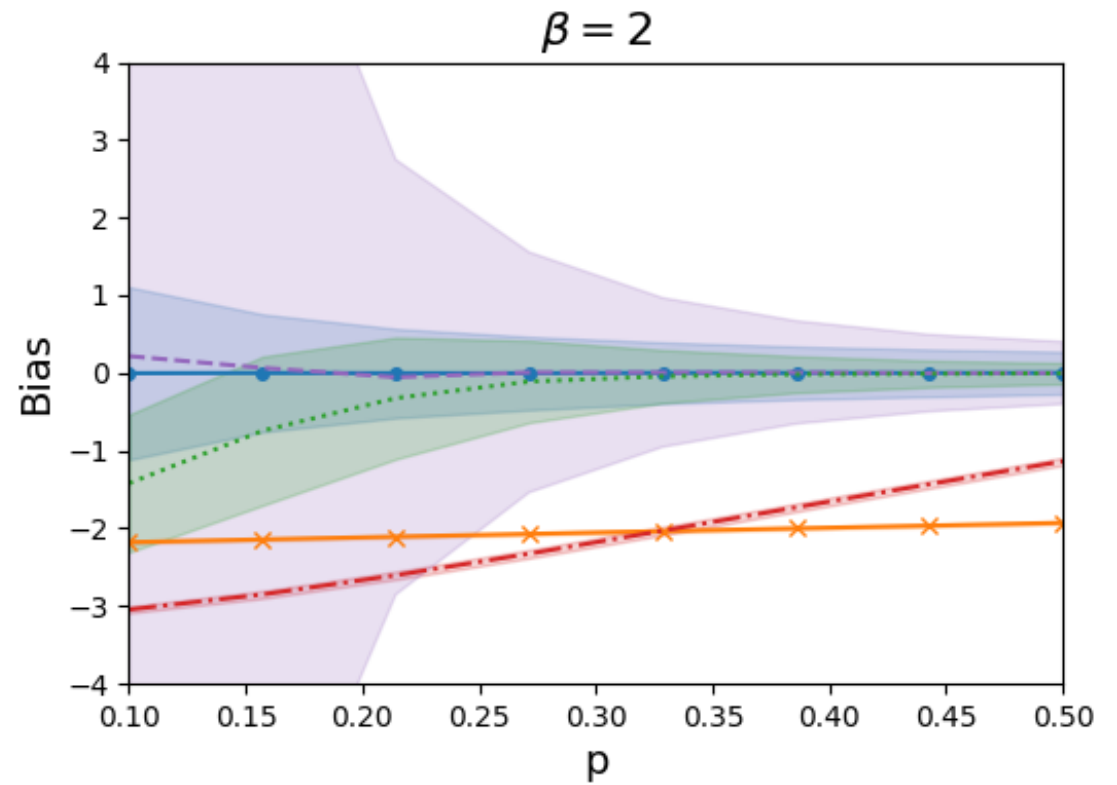
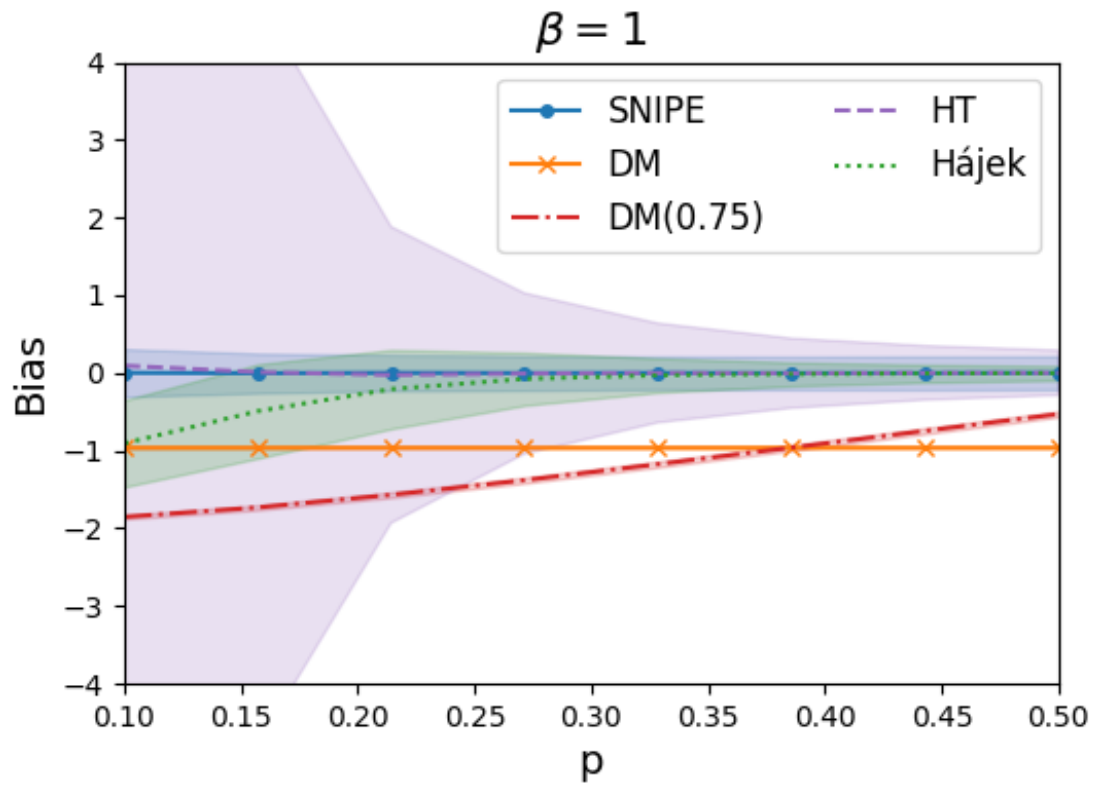
Incorporates:

- Homophily, heterogeneous treatments, degree-dependent effects

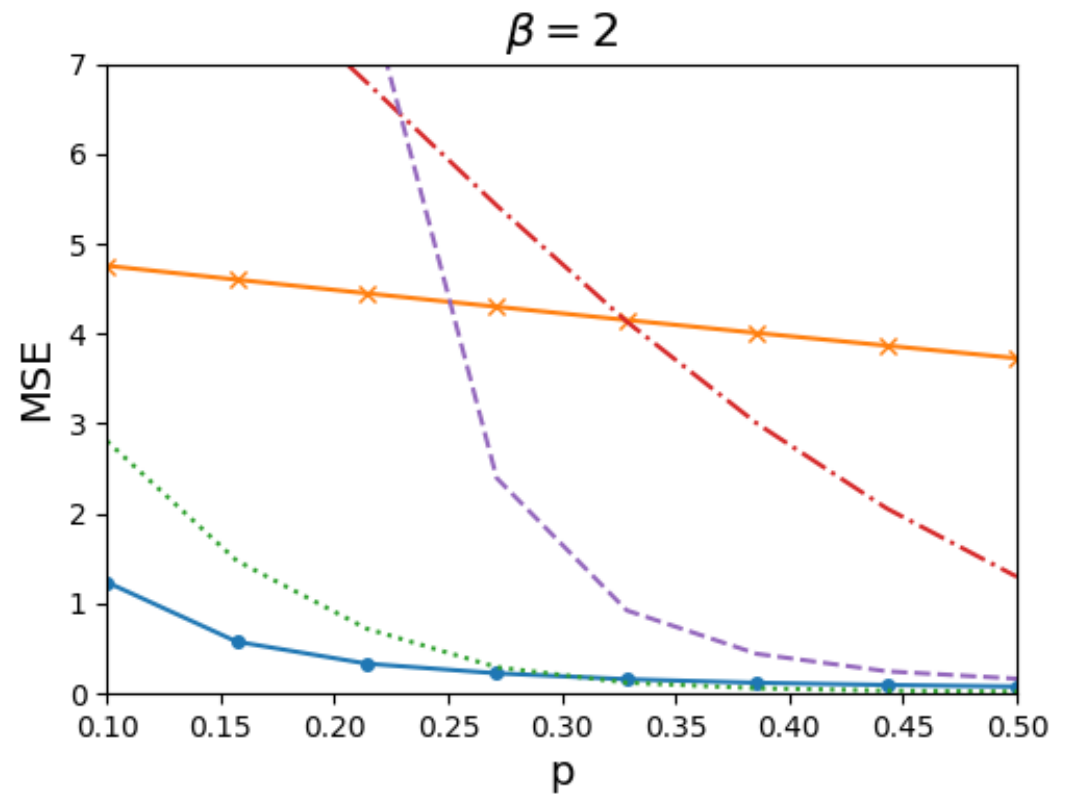
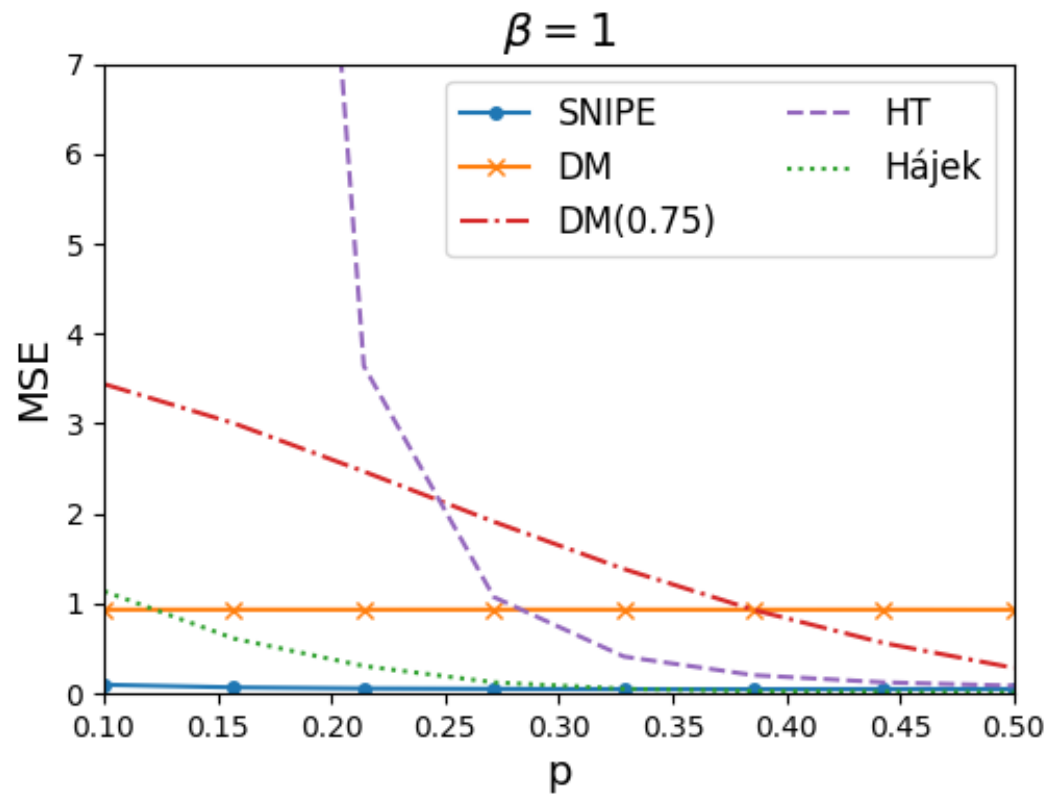
Leskovec, Jure , Andrej Krevl. "SNAP Datasets: Stanford Large Network Dataset Collection." . (2014).

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Analyzing the SNIPE Estimator



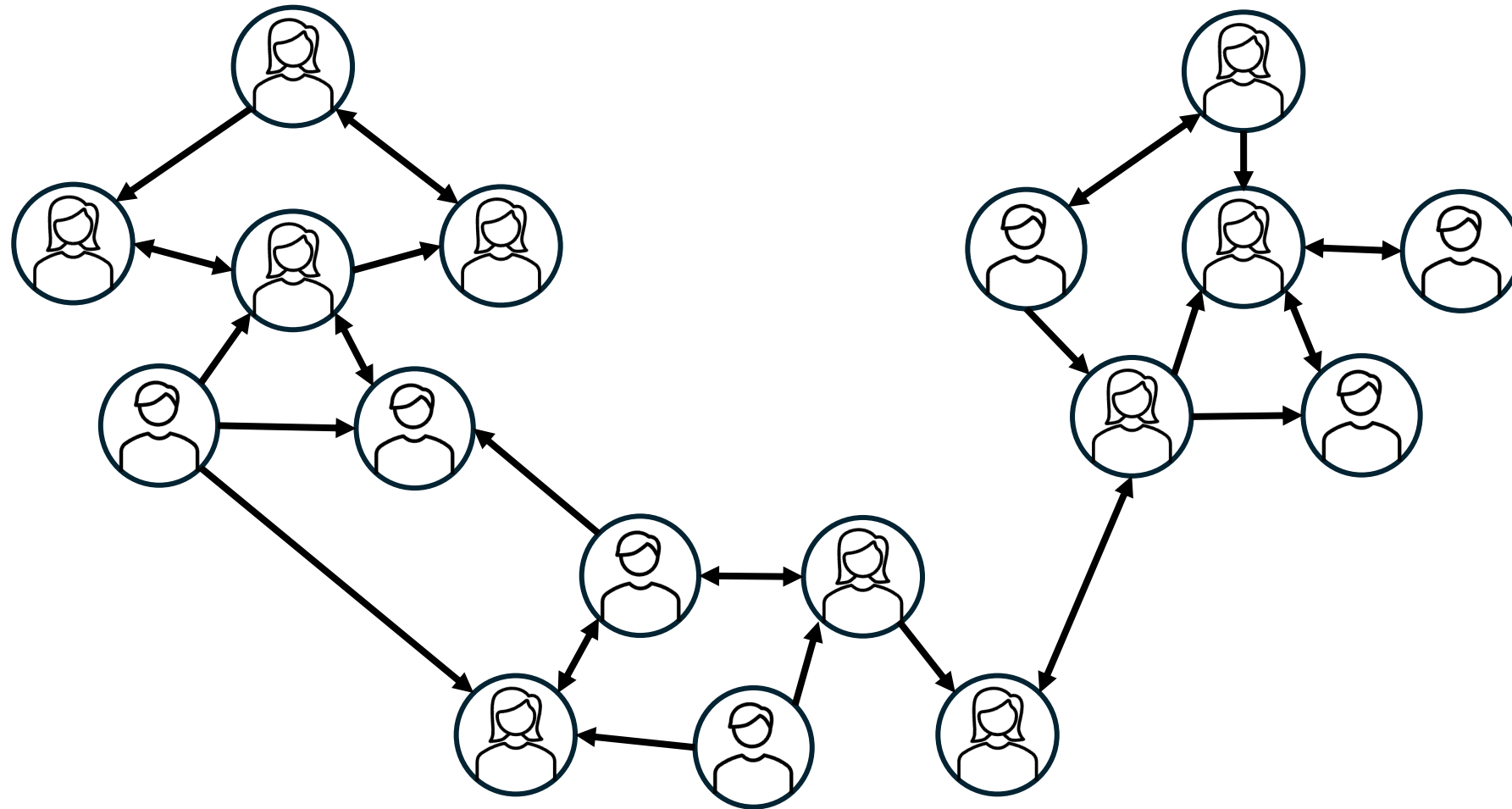
Analyzing the SNIPE Estimator



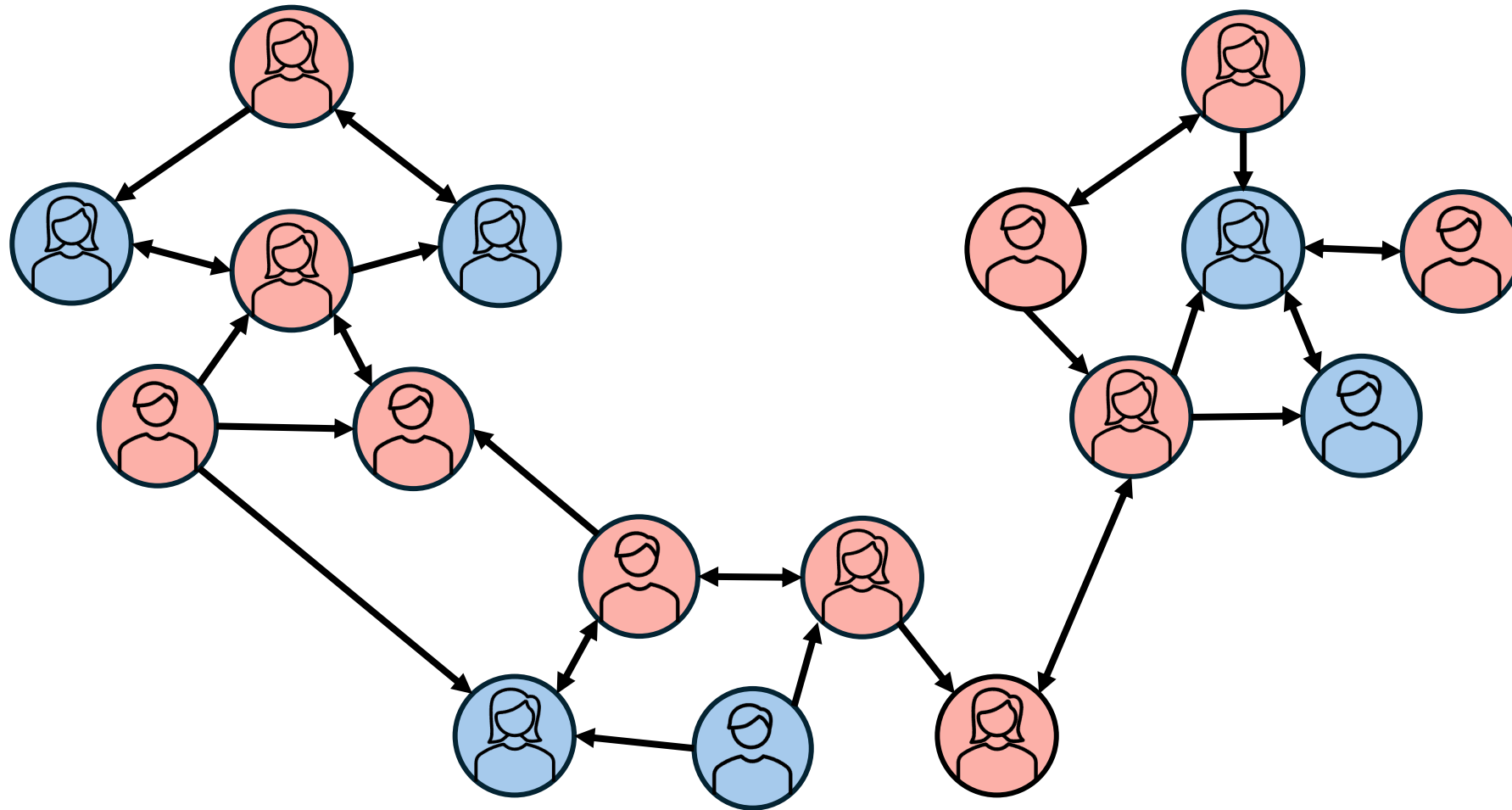
Estimating TTE under arbitrary experimental designs

Eichhorn, Matthew, Samir Khan, Johan Ugander, and Christina Lee Yu. "Low-order outcomes and clustered designs: combining design and analysis for causal inference under network interference." *arXiv preprint arXiv:2405.07979* (2024).

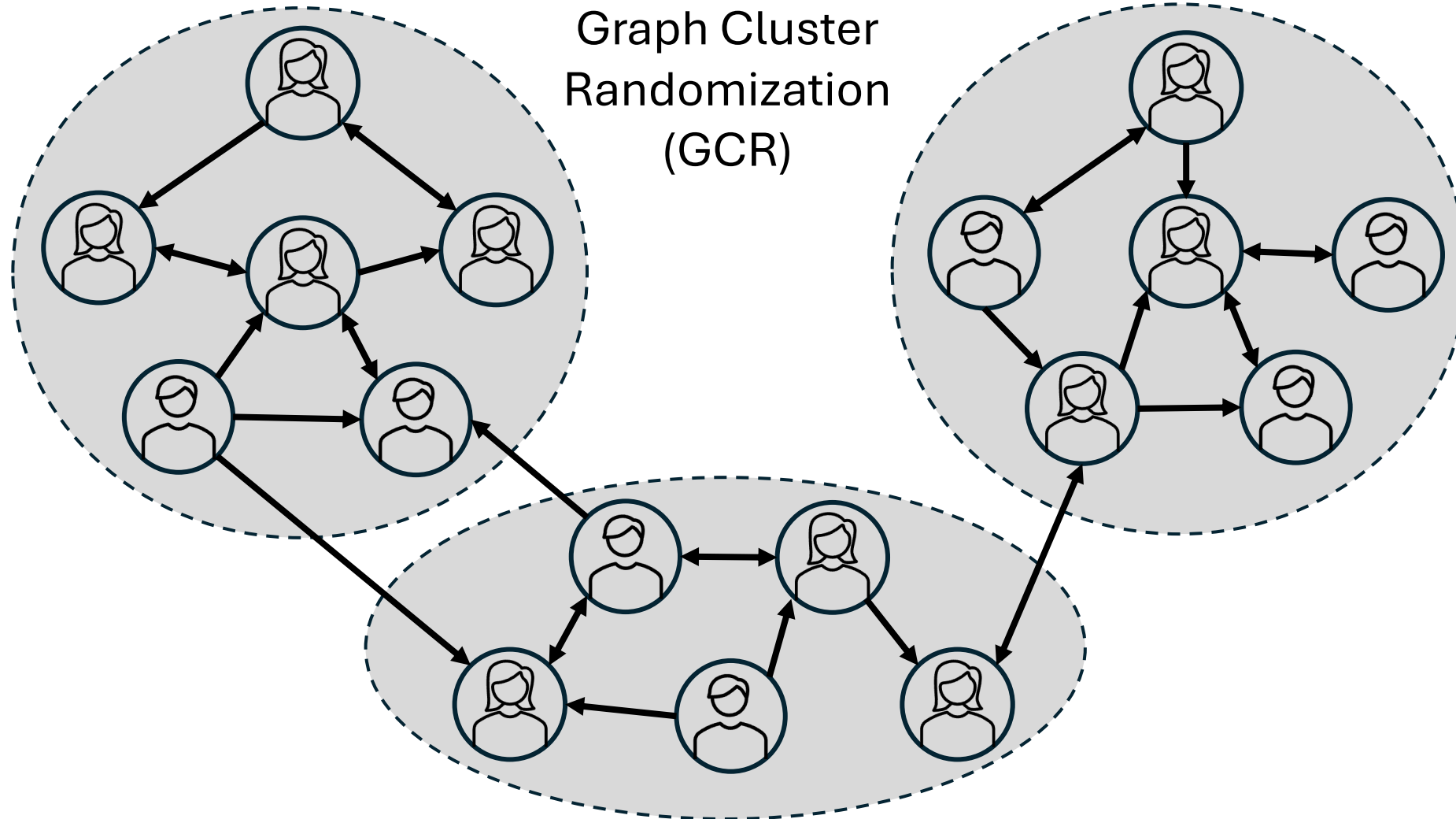
Other Experimental Designs



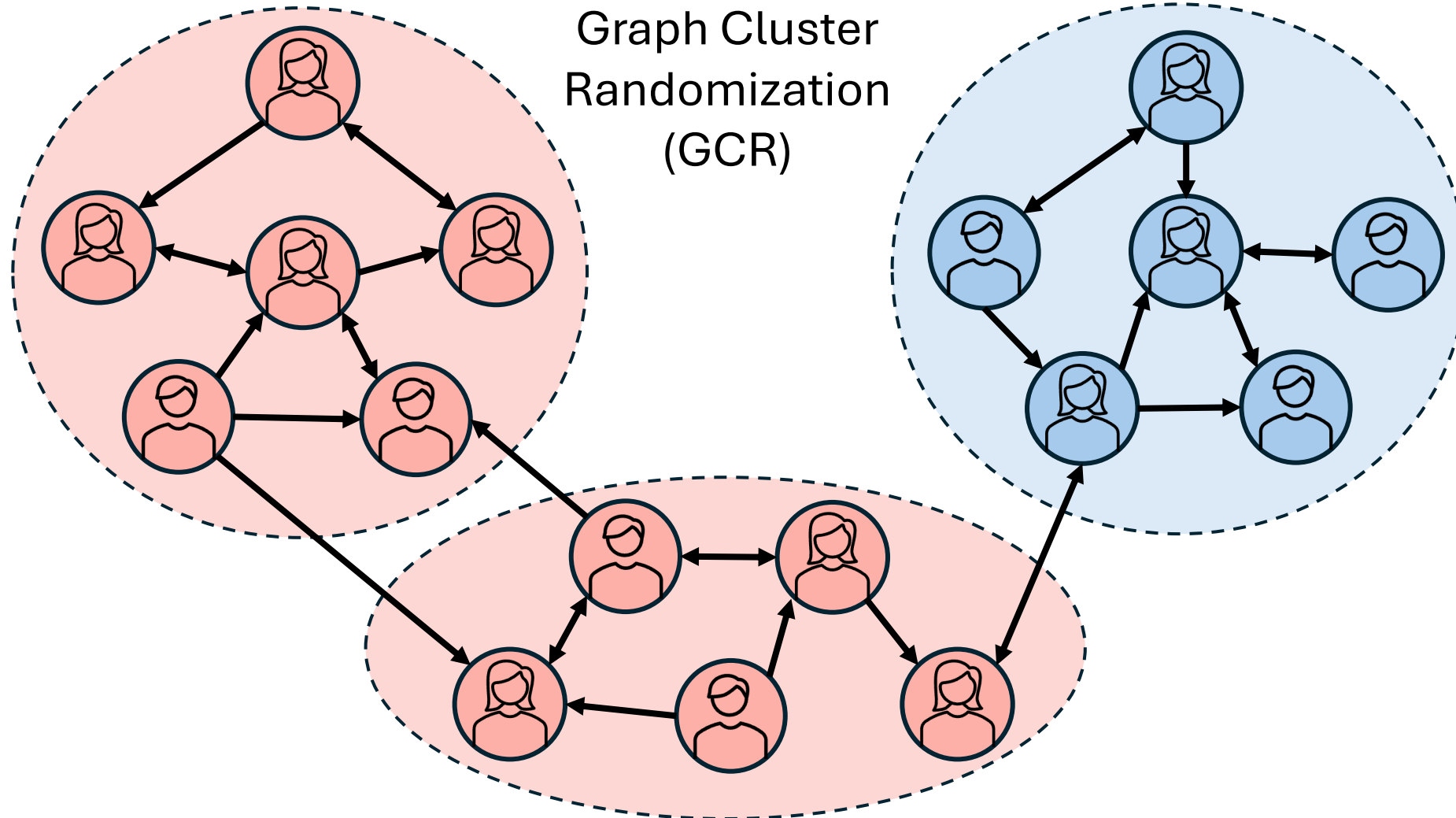
Other Experimental Designs



Other Experimental Designs



Other Experimental Designs



Generalizing the SNIPE Estimator

The identity $\mathbb{E}[Y_i(\mathbf{z}) \tilde{\mathbf{z}}_i] = \mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top] \mathbf{c}_i$ holds for any experimental design

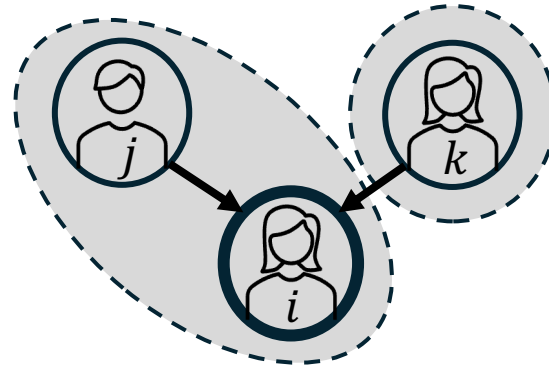
The design matrix $\mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top]$ may not be invertible

Use the (Moore-Penrose) pseudoinverse to estimate $\hat{\mathbf{c}}_i = Y_i(\mathbf{z}) \mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top]^\dagger \tilde{\mathbf{z}}_i$

Pseudoinverse Estimator:

$$\widehat{\text{TTE}}_{\text{PI}} = \frac{1}{n} \sum_{i=1}^n Y_i(\mathbf{z}) \left\langle \mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top]^\dagger \boldsymbol{\theta}_i, \tilde{\mathbf{z}}_i \right\rangle$$

Example: Bernoulli GCR



$\beta = 1$:

$$\mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top] = \begin{array}{c} \begin{array}{cccc} \emptyset & \{i\} & \{j\} & \{k\} \end{array} \\ \left[\begin{array}{cccc|c} 1 & p & p & p & \emptyset \\ p & p & p & p^2 & \{i\} \\ p & p & p & p^2 & \{j\} \\ p & p^2 & p^2 & p & \{k\} \end{array} \right] \end{array}$$

$\beta = 2$:

$$\mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top] = \begin{array}{c} \begin{array}{cccccc} \emptyset & \{i\} & \{j\} & \{i,j\} & \{k\} & \{i,k\} & \{j,k\} \end{array} \\ \left[\begin{array}{cccccc|c} 1 & p & p & p & p & p^2 & p^2 & \emptyset \\ p & p & p & p & p^2 & p^2 & p^2 & \{i\} \\ p & p & p & p & p^2 & p^2 & p^2 & \{j\} \\ p & p & p & p & p^2 & p^2 & p^2 & \{i,j\} \\ p & p^2 & p^2 & p^2 & p & p^2 & p^2 & \{k\} \\ p^2 & p^2 & p^2 & p^2 & p^2 & p^2 & p^2 & \{i,k\} \\ p^2 & p^2 & p^2 & p^2 & p^2 & p^2 & p^2 & \{j,k\} \end{array} \right] \end{array}$$

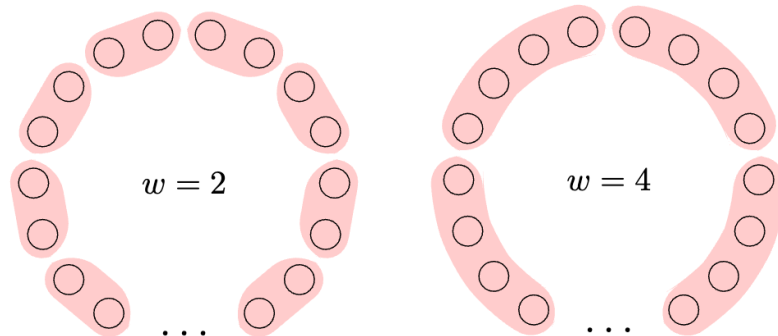
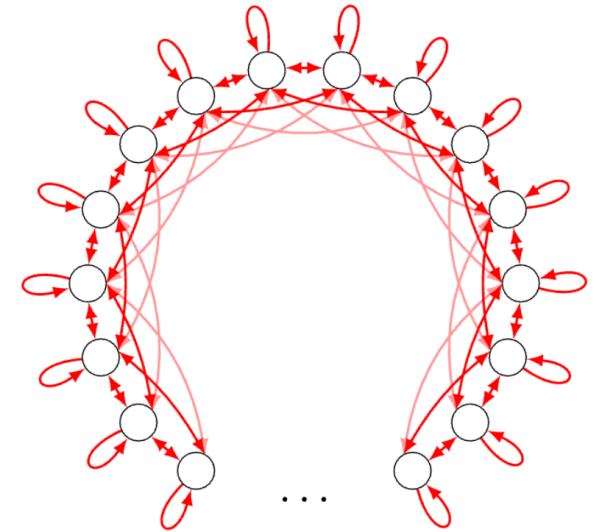
PI Estimator with Bernoulli GCR Designs

Toy experiment on powers of a cycle graph

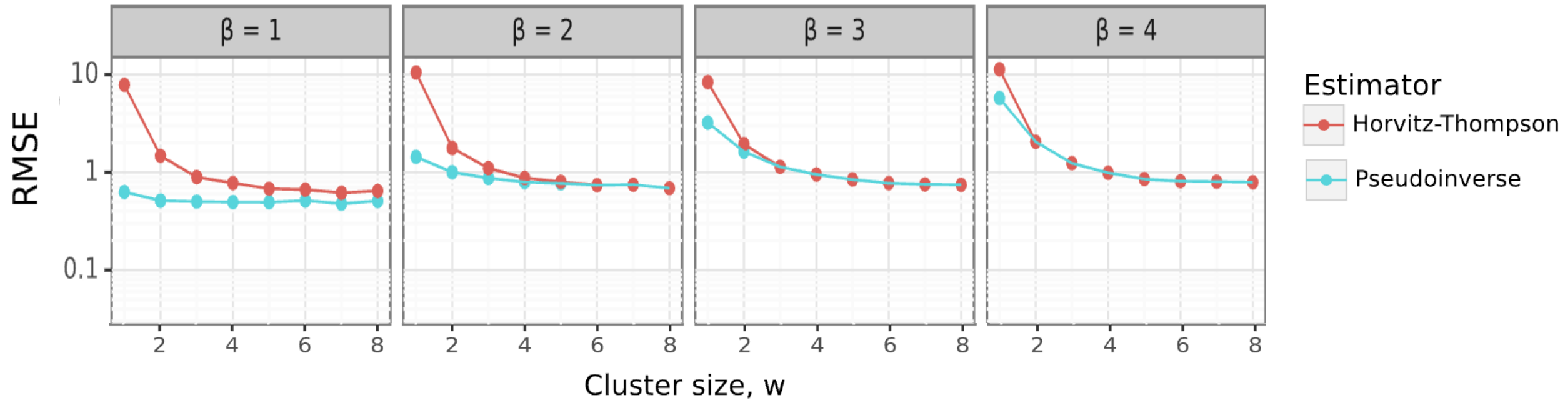
- Restricted growth graphs
- Clustering reduces error of HT Estimator

Compare against PI estimator for different values of β

Consider *contiguous clusterings* of various sizes w



PI Estimator with Bernoulli GCR Designs



Larger clusters = Fewer vertices with “cross cluster” neighbors (HT improves)

Larger β = Weaker Modeling Assumptions (PI gets worse, HT unaffected)

“Best of Both Worlds” Tradeoff

Theoretical Results

Bias:

$$|\mathbb{E}[\widehat{\text{TTE}}_{\text{PI}}] - \text{TTE}| \leq O\left(\frac{1}{n} \sum_{i=1}^n \left\| \left(\mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top]^\dagger \mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top] - I \right) \theta_i \right\|_2\right)$$

Unbiased when each θ_i lies in the column space of $\mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top]$

Variance:

$$\text{Var}(\widehat{\text{TTE}}_{\text{PI}}) \leq O\left(\frac{1}{n^2} \sum_{i=1}^n \sum_{j=1}^n \gamma_i \gamma_j \cdot \mathbb{I}(\tilde{\mathbf{z}}_i \not\perp \tilde{\mathbf{z}}_j)\right)$$

$\gamma_i = \sqrt{|S_i^\beta| \cdot \theta_i^\top \mathbb{E}[\tilde{\mathbf{z}}_i \tilde{\mathbf{z}}_i^\top]^\dagger \theta_i}$ measures “sensitivity” of unit i to randomized design

Specialized to Bernoulli GCR

- $\widehat{\text{TTE}}_{\text{PI}}$ is unbiased
- $\tilde{\mathbf{z}}_i \not\perp \tilde{\mathbf{z}}_j$ when i and j have neighbors in the same cluster
- $\gamma_i = \begin{cases} o(d_i^\beta \cdot p^{-|C(N_i)|}) & |C(N_i)| < \beta \\ o(d_i^\beta \cdot |C(N_i)|^\beta \cdot p^{-\beta}) & |C(N_i)| \geq \beta \end{cases}$
 - Stronger assumption on graph
 - Stronger assumption on outcomes

Variance	Unit Randomization	Cluster Randomization
General Interference	$\exp(d)$	$\exp(C(N_i))$
β -Order Interactions	$\exp(\beta)$	$\exp(\min(\beta, C(N_i)))$

Selecting an Experimental Design

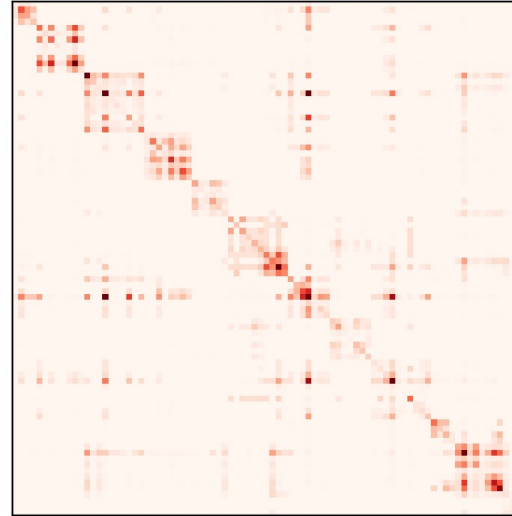
Eichhorn, Matthew, Samir Khan, Johan Ugander, and Christina Lee Yu. "Low-order outcomes and clustered designs: combining design and analysis for causal inference under network interference." *arXiv preprint arXiv:2405.07979* (2024).

Visualizing the Variance

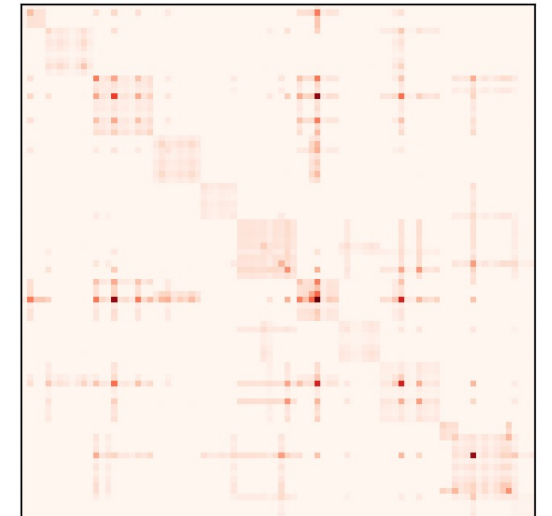
Variance contribution of each vertex pair in a small collaboration network

$$\text{Var}(\widehat{\text{TTE}}_{\text{PI}}) = \frac{1}{n^2} \sum_{i=1}^n \sum_{j=1}^n \text{Cov}(w_i Y_i, w_j Y_j)$$

Unit Bernoulli



Bernoulli GCR



Visualizing the Variance

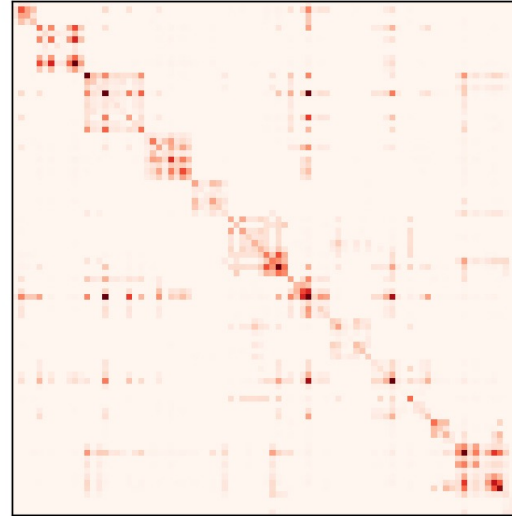
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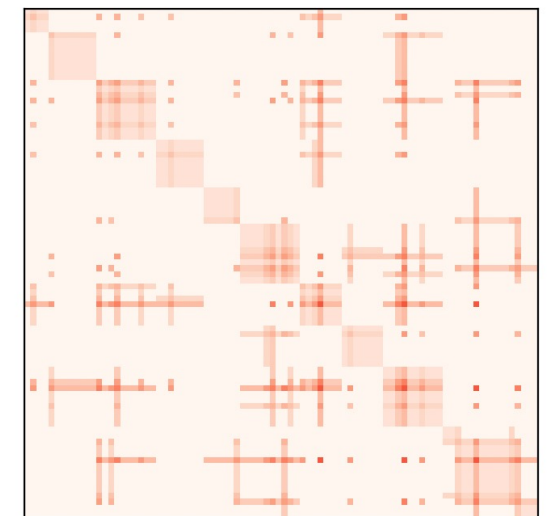
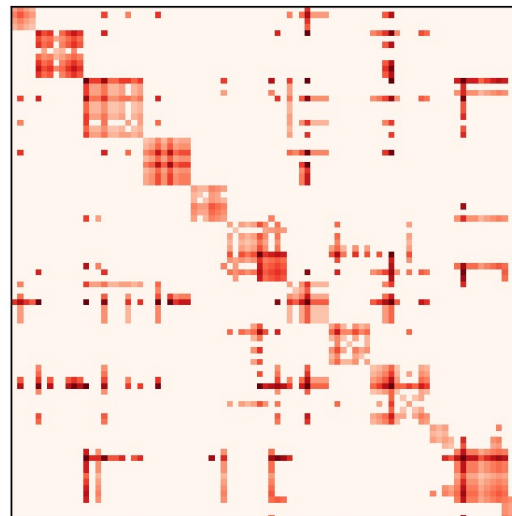
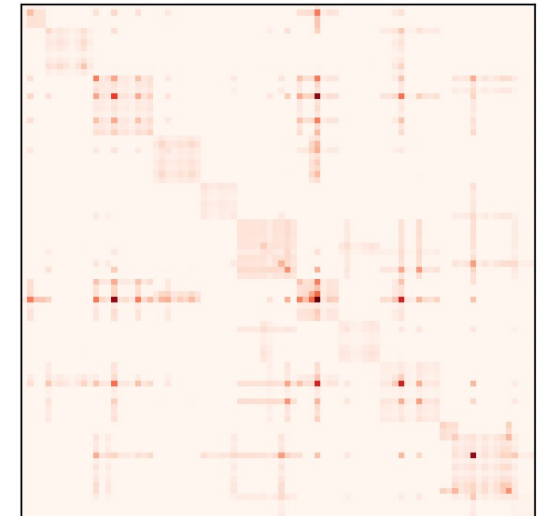
Contributions to the Variance Bound

$$\gamma_i \cdot \gamma_j \cdot \mathbb{I}(\tilde{\mathbf{z}}_i \perp \tilde{\mathbf{z}}_j)$$

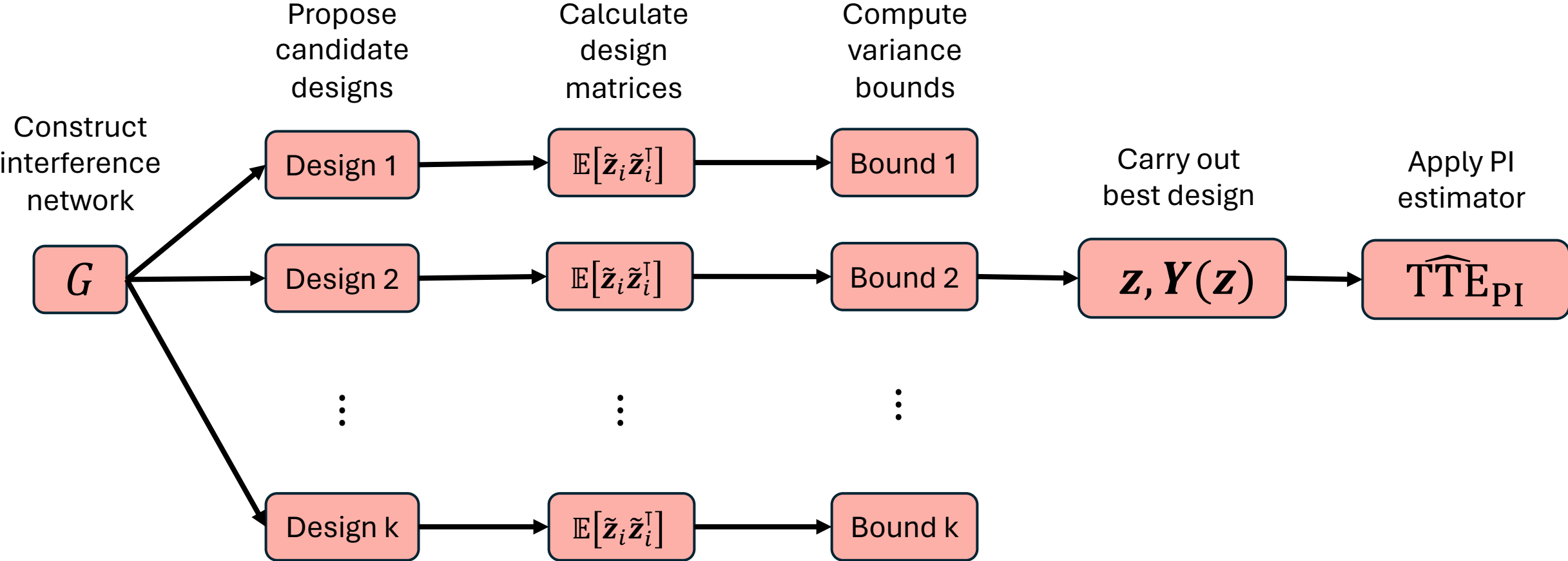
Unit Bernoulli



Bernoulli GCR

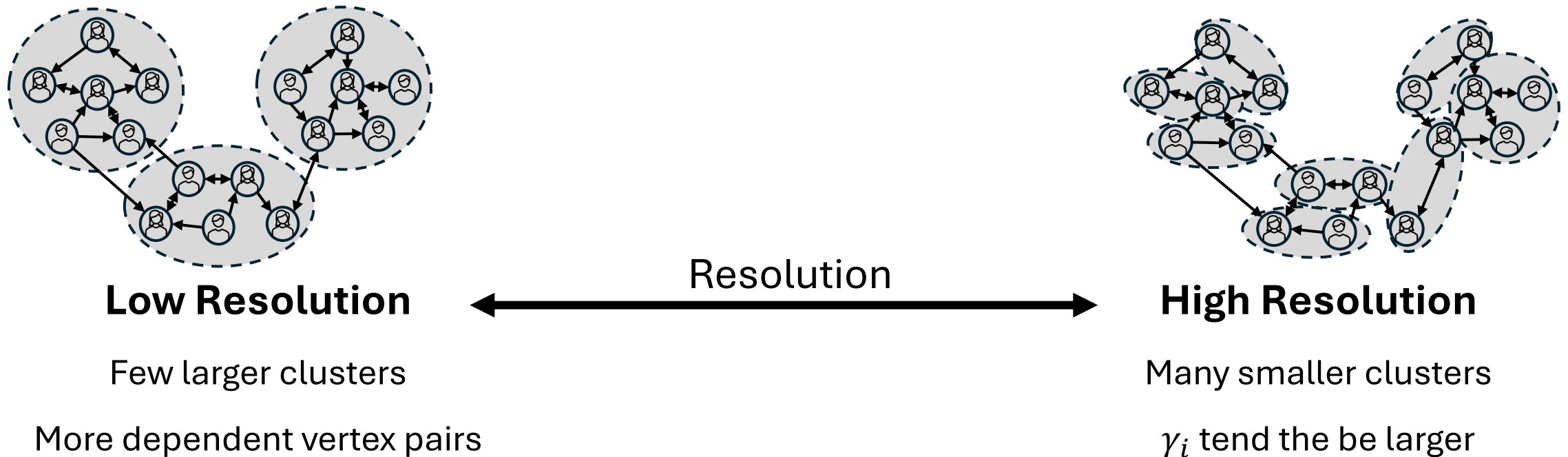


Experimental Pipeline



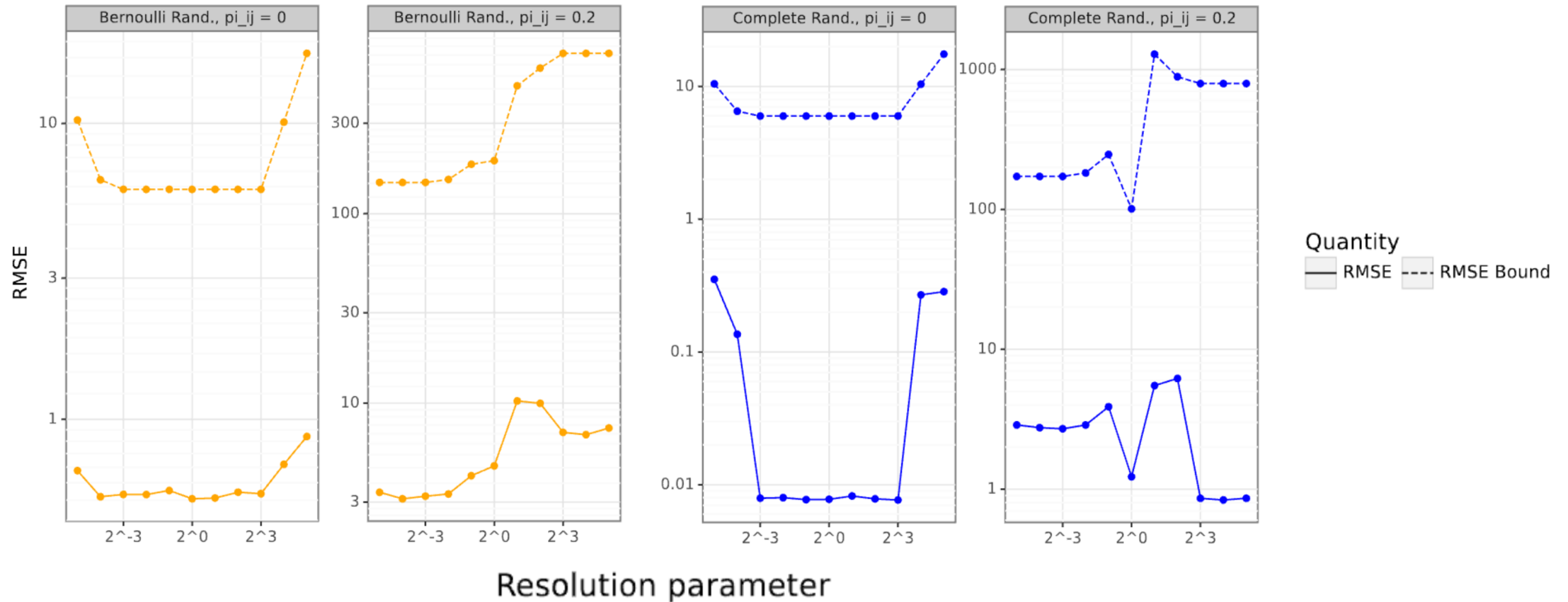
Example: Clustering Stochastic Block Models

At what *Louvain clustering resolution* does the \widehat{TTE}_{PI} estimator with Bernoulli GCR have minimum variance?



Example: Clustering Stochastic Block Models

Though the theoretical bounds are loose, they capture the behavior of the estimator



Main Takeaways

- β -order interactions
 - Rich framework for modeling interference
 - Hierarchy of sparse bases for outcome parameterization
- Pseudoinverse estimators
 - Leverage outcome structure to give improvements over existing approaches
 - Can be adapted to arbitrary experimental designs
- Novel bias and variance results in terms of properties of the design
 - Provide a principled way to select an experimental design

Ongoing Question:

How can we best select a (design, estimator) pair?

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SNIFE Estimator



Pseudoinverse Estimators



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Toulis, Panos, and Edward Kao. "Estimation of causal peer influence effects." *International conference on machine learning*. PMLR, 2013.

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Novel experimental designs under general interference (purple in chart):

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